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DISTRIBUTED BROADCAST PROTOCOL IN COGNITIVE RADIO ADHOC NETWORKS

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***Abstract*—joint design of Resource allocation and routing algorithms in cognitive radioWMNs. To share the spectrum with primary users the mesh nodes utilize cognitive overlay mode. Depending on the traffic characteristics and primary user activities, the available spectrum resources will vary between mesh transmission attempts, posing a challenge to dealing with guarantee timely delivery of the network traffic. Prior to each transmission, the mesh nodes then senses the wireless medium to identify available spectrum resources.The system is analyzed from a queuing theory perspective, to capture the channel availability dynamics and the joint routing and resource allocation problem is constructed as a non-linear integer programming issue.**

The objective is to minimize the aggregate end-to-end delay of all the network flows. A distributed solution scheme is developed based on the Lagrangian dual problem. Numerical results demonstrate the convergence of the distributed solution procedure to the optimal solution, as well as the performance gains compared to other design methods. It is shown that the joint design scheme can accommodate double the traffic load, or achieve half the delay compared to the disjoint methods. It is shown that the joint design scheme can accommodate double the traffic load, or achieve half the delay compared to the disjoint methods.

Keywords:On Demand Routing Protocol (DORP), Destination-Sequenced Distance-Vector (DSDV) protocol, delay, cognitive, Recursive Algorithm, Dynamic Source Routing and Adhoc network.

I. INTRODUCTION

COGNITIVE radio is a promising technology aiming at better utilization of available channel resources by prescribing the coexistence of licensed (or primary) and unlicensed (secondary or cognitive) radio nodes on the same bandwidth. One of the key challenges in the design of cognitive radio networks is the design of dynamic spectrum allocation algorithms, which enable the cognitive nodes to opportunistically access the available wireless spectrum, without interfering with existing primary nodes. Therefore, dynamic spectrum access techniques have received significant attention. In [2] and [3] the cognitive radio problem was investigated from an information theoretic standpoint. The cognitive transmitter is assumed to transmit at the same time and on the same bandwidth of the primary link. Interference is mitigated through the use of complex precoding techniques that require perfect prior information about the primary signal.

Hence, controlling the interaction between the routing and the spectrum management functionalities is of fundamental importance. While cross layer design principles have been extensively studied by the wireless networking research community, the availability of cognitive and frequency agile devices motivates research on new algorithms and models to study cross-layer interactions that involve spectrum management-related functionalities.

A routing and spectrum selection algorithm for cognitive radio networks was proposed and it chooses the path that has the highest probability to satisfy the demands of secondary users in terms cognitive transmitter is assumed to transmit at the same time of capacity. However, it does not cover the issue of scheduling. In [9], a cross-layer optimization problem for a network with cognitive radios is formulated. The objective is to minimize the required network-wide radio spectrum resources needed to support traffic for a given set of user sessions. The joint routing and resource allocation design has an objective for the minimization of the end-to-end delay and accommodate higher traffic. The performance of the proposed protocol is thoroughly studied and compared to the performance of a disjoint protocol. The disjoint protocol solves the routing problem first and then allocates resources along the constructed routes.

The routing metric used favours links with higher primary idle probability while penalizing the total number of hops. The resource allocation part aims at minimizing the end-to-end delay along the preselected routes.

Interference is mitigated through the use of complex precoding techniques that require perfect prior information about the primary signal. The concept of a time-spectrum block was introduced in and protocols to allocate such blocks were proposed. The authors derived optimal and suboptimal distributed strategies for the secondary users to decide which channels to sense and access under a Partially Observable Markov Decision Process (POMDP) framework. The cognitive radio concept is desirable for a WMNs (WMN) in which a large volume of traffic is expected to be delivered since it is able to utilize spectrum resources more efficiently. Therefore, it improves network capacity significantly. However, the dynamic nature of the radio spectrum calls for the development of novel spectrum-aware routing algorithms.

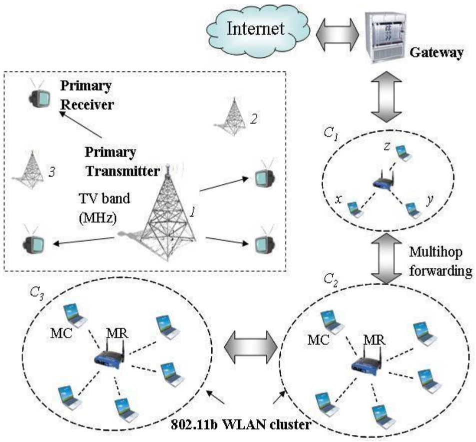


Fig 1 Cognitive Mesh Network

Function Objective	Objective
Spectrum Sensing	Detection of spectrum holes and estimation of their average power Contents.
Predictive Modelling	Prediction of how long the spectrum hole is likely to remain available for Employment by secondary user.
Transmit–Power Control	Maximize the data rate of each user subject to power constraints
Dynamic Spectrum Management	Distribute the spectrum holes fairly among secondary users, bearing in mind usage costs.
Packet Routing	Design a self-organized scheme for routing of packets across the radio network

Table I Functional Objectives of Cognitive Radio

Spectrum Sharing in CR Networks of the wireless channel necessitates coordination of transmission among the CR users. In the CRAHNs, the sensing schedules are determined and controlled by each user and are not synchronized by any central network entity. Thus, the CR ad hoc users independently perform sensing on an on demand basis - i.e., when CR users want to transmit or are requested their spectrum availability by neighbouring users. This closely couples the sensing functionality with spectrum sharing among the CR users that is an integral part of the medium access control (MAC) layer coordination.

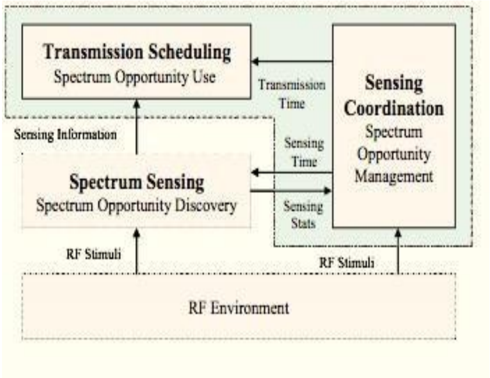


Fig 2 Block Diagram of MAC

Cognitive radios has the following challenges,

Challenge 1 *- The spectrum-awareness designing efficient routing solutions for CRNs requires a tight coupling between the routing module(s) and the spectrum management functionalities such that the routing module(s) can be continuously aware of the surrounding physical environment to take more accurate decisions.*
Challenge 2 *- Setting up of "quality routes in dynamic variable environment and reduce end to end delay the route quality" has to be re-defined such that the timely delivery is guaranteed with lower delay less packets loss.*
Challenge 3 *– Maximum utilization of available spectrum*

The routing and spectrum management algorithms should ensure maximum utilization of available spectrum and accommodate higher traffic.

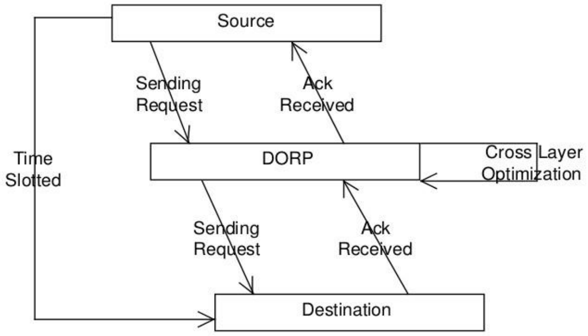
The main objective in this work is to find the best routing and resource allocation strategies in order to minimize the average end-to-end delay of multiple data connections in the cognitive radio based WMNs. Because of the primary nodes activity, the spectrum resources available to the cognitive mesh nodes are varying in both space and time. Therefore, any successful routing strategy will have to work closely with the resource allocation strategy in order to make sure that any selected route will have enough resources available to guarantee the required Quality of Services (QoS). Because of this strong interdependence between the routing and resource allocation strategies, we propose to deal with the routing and resource allocation strategies in a joint fashion rather than separating the two problems.

Before presenting joint design strategy we need first to analyze the effect of the routing and resource allocation decisions on the network performance. This is achieved by relying on queuing theory to model the different aspects of the cognitive mesh network and to form a basis for our routing and resource allocation protocol design.

II.EXISTING SOLUTION

The existing solution is a design for routing and resource allocation in a joint fashion for cognitive radio mesh networks. The methodology using CRAT end to delay drastically and increases the maximum throughput. But it does not extend its support to any Wireless Sensor networks that are random and mesh networks.

Also the existing solution concentrates only on the delay and throughput of the cognitive mesh networks. Various network parameters need to be considered for the throughput like packet ratio, channel measurement, Quality of Service and packet delivery rate.



III.PROPOSED MODEL

The proposed solution deals with extending the CRAT protocol to be applied in Wireless Sensor networks like random and mesh networks. The methodology is also used to validate the network throughput using the other parameters like Quality of Service, Channel Measurement, Packet loss and Packet delivery rate.

The proposed solution also aims in reducing the end to end delay and increase the throughput by applying the Recursive Algorithm and Hidden Terminal Communication concept to the network using CRAT Protocol.

Quality of service (QoS) is the overall performance of a telephonyparticularly the performance seen by the users of the network. To quantitatively measure quality of service, several related aspects of the network service are often considered, such as error rates, bandwidth, throughput, transmission delay, availability, jitter, etc. Quality of service is particularly important for the transport of traffic with special requirements. In particular, much technology has been developed to allow computer networks to become as useful as telephone networks for audio conversations, as well as supporting new applications with even stricter service demands.

Packet Delivery Rate in telecommunication networks, the transmission time, is the amount of time from the beginning until the end of a message transmission. In the case of a digital message, it is the time from the first bit until the last bit of a message has left the transmitting node.

The packet transmission time in seconds can be obtained from the packet size in bit and the bit ratein bit/sas:

Packet transmission time = Packet size / Bit rate

Example: Assuming 100 Mbit/s Ethernet, and the maximum packet size of 1526 bytes, results in Maximum packet transmission time = 1526×8 bit / (100 × 106 bit/s) ≈ 116 µs

The packet delivery time or latencyis the time from the first bit leaves the transmitter until the last is received.

In the case of a physical link, it can be expressed as:

Packet delivery time = Transmission time + Propagation delay

In case of a network connection mediated by several physical links and forwarding nodes, the network delivery time depends on the sum of the delivery times of each link, and also on the packet queuing time (which is varying and depends on the traffic load from other connections) and the processing delay of the forwarding nodes. In wide-area networks, the delivery time is in the order of milliseconds.The network throughputof a connection with flow control, for example a TCPconnection, with a certain window size(buffer size), can be expressed as:

Network throughput ≈ Window size / roundtrip time

In case of only one physical link between the sending and transmitting nodes, this corresponds to:

Link throughput ≈ Bitrate × Transmission time / roundtrip time

A. *Recursive Algorithm:*

The network utilization is optimized using thepriority mechanisms, while meeting the requirements of each type of traffic. By using the loss priority bit capability the user may generate different priority traffic flows. When buffer overflow occurs, the packets from the low priority flow can be discardedselectively by network elements. Priority mechanisms can be classified into two categories: time and space priority.

Time priority mechanisms control the transmission sequences of buffered packets whereas space priority mechanisms control the access to buffer. Chipalkatti et al. studied the performance of time priority mechanisms including Minimum Laxity Threshold (MLT) and Queue Length Threshold (QLT) under mixed traffic of real-time and non-real-time packets. The First In First Out (no special priority) policy causes relatively high losses for real-time traffic while providing low delays for non-real-time traffic. The converse holds true when priority is given to real-time traffic unconditionally. Space (or loss) priorities propose to provide several grades of services through the selectively discarding low priority packets. This type of priority mechanisms exploit the fact that low priority packets may be discarded in case of congestion, without significantly compromising the source‟sQoS requirements.

The investigated space priority mechanisms are the Pushout mechanisms and Partial Buffer Sharing (PBS). In both, each source allocates every packet with a priority level, indicating a high priority and low priority packet. The description of several space priority mechanisms are given below,

The high priority packet may enter the queue even though the queue is full in the pushout mechanism, by replacing it with a low priority packet already in queue. If a low priority packet arrives at the queue when it is full, it will be discarded. The vital packets will only be lost when the queue is full and there are no ordinary packets waiting for service in the queue. The pushout policy based onMulti-queue can achieve service differentiation, highest buffer sharing and fairness assurance.

A Proportional Loss Rate (PLR) dropper is presented in [8] to support proportional differentiated services. With the Partial Buffer sharingmechanism, both high and low priority packets are accepted by the queue until it reaches a threshold level. When this threshold has been completed, only the high priority packets will be accepted, provided that queue is not full. The threshold is constant in all the existing PBS schemes and do not change during operation. The independent assumption underrates the consecutive packet loss probabilities. The high correlation between consecutive packet losses may confine the efficiency of forward error correction.

1. First Come First Serve scheduling methods
2. Decentralized Pre-emptive Scheduling using content delivery Network
3. Decentralized Non-Pre-emptive Scheduling using content delivery Network
4. Space Priority Mechanisms using recursive Algorithm
5. Partial Buffer Sharing using recursive Algorithm.

IV.EXPERIMENTAL RESULTS

NS2.35 Network simulator is used to simulate a wireless network with CRAT Protocol(applied Recursive Algorithm). The simulation results are given below,

Delay analysis:

Delay is referred to the time taken for a data packetto be transmitted across a networkfrom source to destination. delay has to be reduced in CRAT protocol so as to improve the reliability of the transmission. Delay for the existing system using CRAT protocol and proposed CRAT protocol (Recursive Algorithm) is given below.

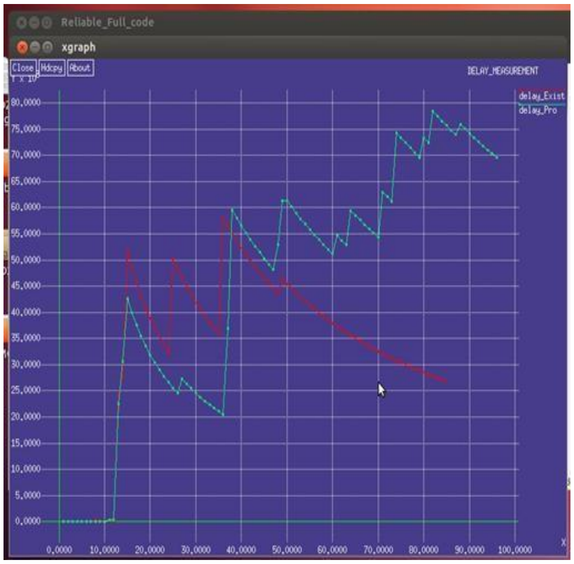


Fig 4 Comparison of delay for both existing and proposed system.

*Throughput analysis***:**

Throughput or the network throughput is the rate of successful delivery of message over a communication channel. The data to which these messages belong to may be delivered over a logical link,physical or it can pass through a certain network node. Throughput is calculated in bits per secondand also in data packetsper second or data packets per slot (p/s or pps). In the existing system throughput is calculated using CRAT protocol and in the proposed system it is calculated using CRAT protocol (Recursive Algorithm applied) the graphs are simulated and are shown below.

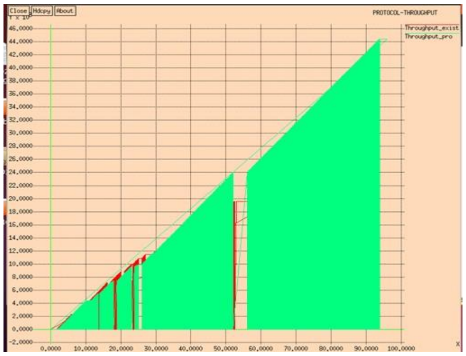


Fig 5 Comparison of Throughput for both existing and proposed system

Loss analysis:

Packet loss happens when one or more packetsof data across a computer networkfail to reach their destined destination. Packet loss for both existing and proposed system is simulated using CRAT and CRAT protocol

(Recursive Algorithm applied) and their graphs are simulated.

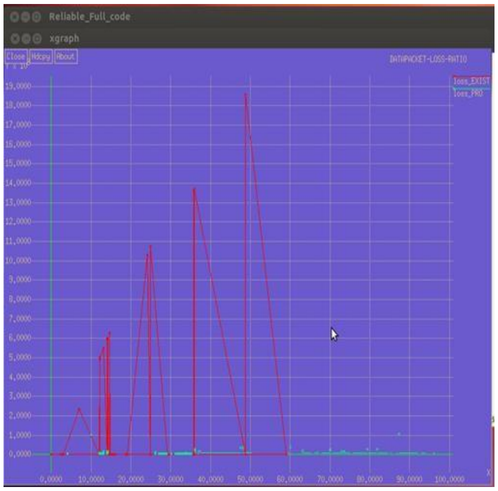


Fig 6 Comparison of Loss Ratio for both existing and proposed system

Packet delivery ratio analysis:

Packet delivery ratio is the ratio of the number of data packets delivered to the destination. This portrays the level of the data received at the destination. Greater the value of the packet delivery ratio, better the performance of the protocol. The ratio of successfully delivered packets to a destination is compared to the number of packets that have been sent by the sender.

$\sum$ Number of packets received / $\sum$ Number of packets sent.

Fig 7 Comparison of Packet Delivery Ratio

Source frequency:

The source frequency is calculated for both existing and proposed system using DORP and CRAT protocol (Recursive Algorithm applied) and their comparison graph is shown below.

Fig 8 Comparison of Source Frequency for both existing and proposed system

Destination frequency:

The Destination frequency has to be improvised so as to improve reliability. Therefore an analysis is made for the destination frequency using DORP protocol in existing system and the proposed system analysis is made using CRAT protocol (Recursive Algorithm applied) and the comparison for existing and proposed system are given.

Fig 9 Comparison of Destination Frequency for both existing and proposed system

Channel measurement:

Channel measurements are necessary for the design of wireless system. The wireless channel determines the peak performance limits of any communication system. In the start of cellular communications, path loss and fading of narrow band channel were the important figures of merit. This has undergone changes with wide band multi antenna and the multiuser system. The new importance of the radio channel became obvious that is the channels frequency directivity, selectivity, Polari metric properties and their relation to the users.

Fig 10 Comparison of Channel Measurement

V. FUTURE ENHANCEMENT

Even though all kinds of faults has been recovered using this protocol, there is 26% in packet delivery rate. So we will concentrate more on this error and make it completely error free in future enhancement.

VI.CONCLUSION

Resource allocation schemes andJoint design of routing in cognitive radio based Wireless Mesh Networks. The cross-layer design schemes are important since disjoint design strategies leads to lower performance (in terms of delay or the number of allowable traffic streams). It is clear that the proposed design scheme with CRAT Protocol using the Recursive Algorithm can hold higher traffic load, and achieve lower delay. CRAT Protocol (Recursive Algorithm applied) will improve the other parameters in the WMNsthereby enhancing the performance of WMNs. The other improved parameters in the Mesh/Random network areChannel Measurement, Packet delivery rate, Packet loss and Quality of Service.

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